

DATA AND COMPUTER COMMUNICATIONS

Lecture 3 Data Link Layer - Data Link Control Protocols

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Based on Lecture slides by William Stallings

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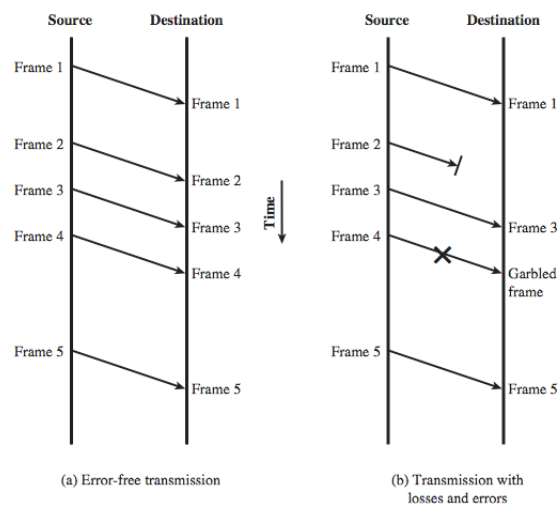
DATA LINK CONTROL PROTOCOLS

- need layer of logic above Physical
- to manage exchange of data over a link
 - frame synchronization
 - flow control
 - error control
 - addressing
 - control and data
 - link management

FLOW CONTROL

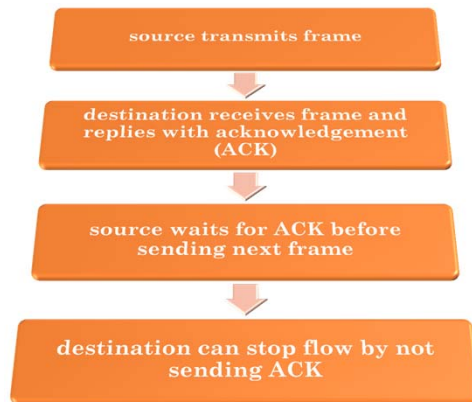
- ensure sending entity does not overwhelm receiving entity
 - by preventing buffer overflow
- influenced by:
 - transmission time
 - time taken to emit all bits into medium
 - propagation time
 - time for a bit to traverse the link
- assume here no errors but varying delays

MODEL OF FRAME TRANSMISSION



STOP AND WAIT

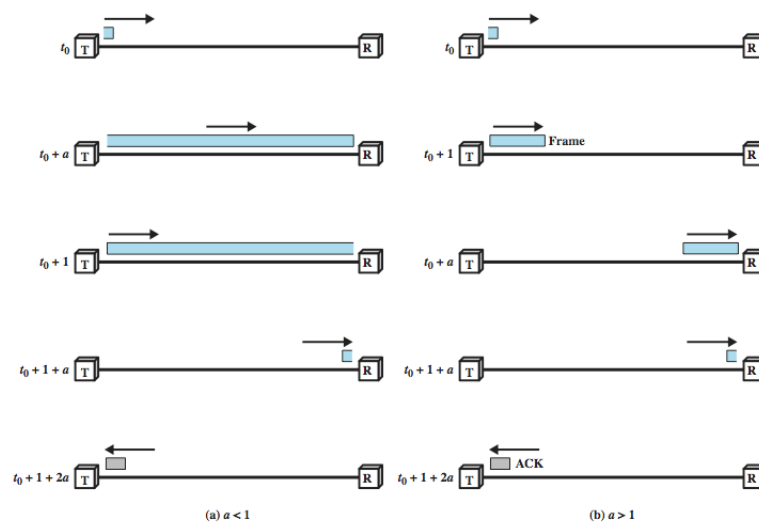
- simplest form of flow control



- works well for a message sent in a few large frames

- stop and wait becomes inadequate if large block of data is split into small frames by source

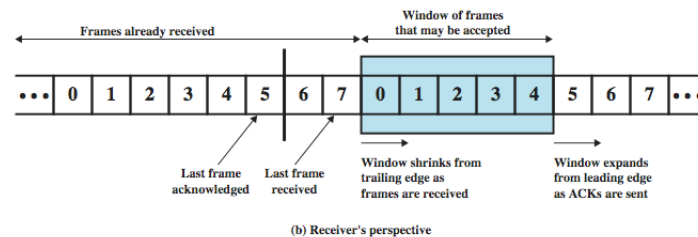
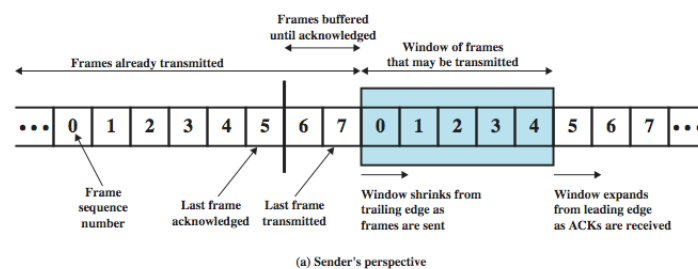
STOP AND WAIT LINK UTILIZATION



SLIDING WINDOWS FLOW CONTROL

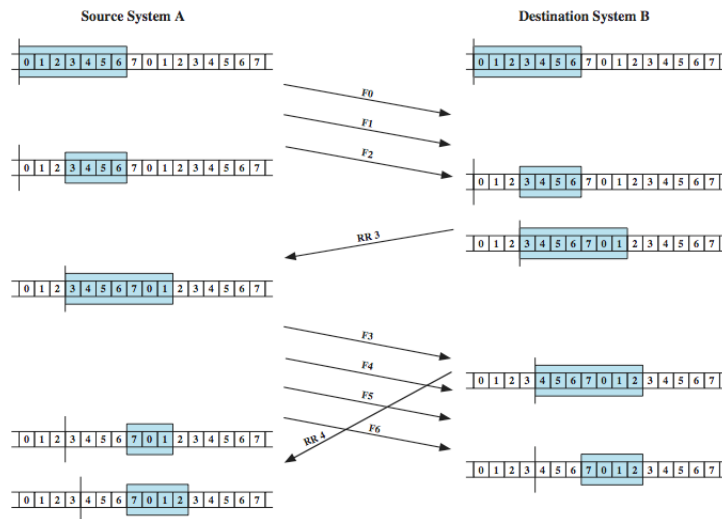
- allows multiple numbered frames to be in transit
- receiver has buffer W long
- transmitter sends up to W frames without ACK
- ACK includes number of next frame expected
- sequence number is bounded by size of field (k)
 - frames are numbered modulo 2^k
 - giving max window size of up to $2^k - 1$
- receiver can ack frames without permitting further transmission (Receive Not Ready)
- must send a normal acknowledge to resume
- if have full-duplex link can piggyback ACKs

SLIDING WINDOW DIAGRAM



SLIDING WINDOW EXAMPLE

<http://www.humboldt.edu/~aeb3/telecom/SlidingWindow.html>



ERROR CONTROL

○ detection and correction of errors such as:

- lost frames
- damaged frames

○ common techniques use:

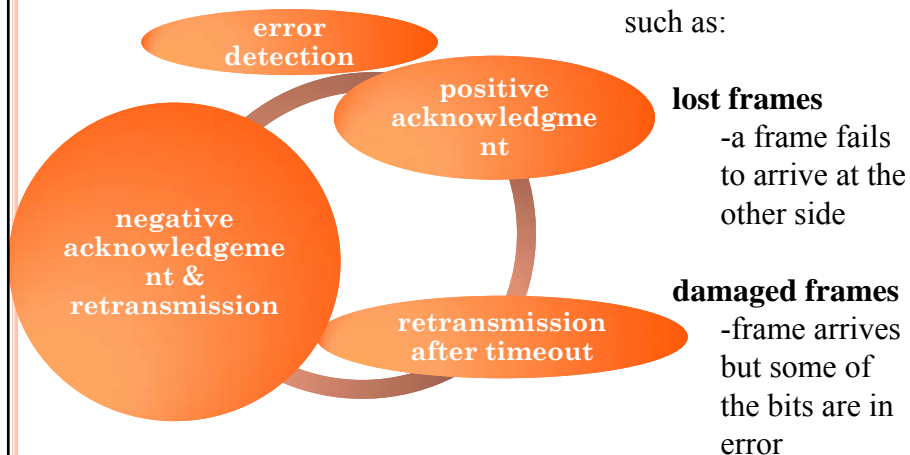
- error detection
- positive acknowledgment
- retransmission after timeout
- negative acknowledgement & retransmission

STOP AND WAIT

- source transmits single frame
- wait for ACK
- if received frame damaged, discard it
 - transmitter has timeout
 - if no ACK within timeout, retransmit
- if ACK damaged, transmitter will not recognize it
 - transmitter will retransmit
 - receiver gets two copies of frame
 - use alternate numbering and ACK0 / ACK1

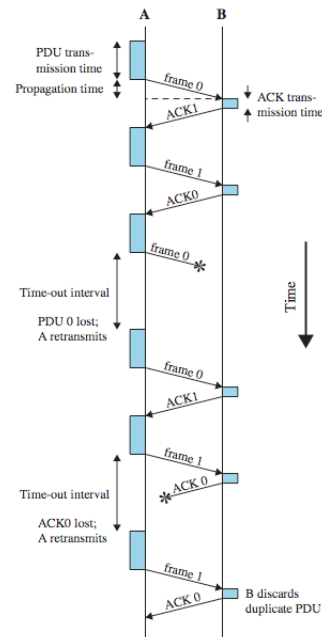
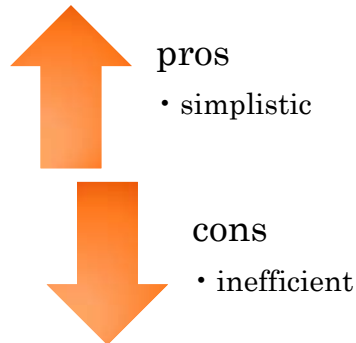
ERROR CONTROL TECHNIQUES

detection and correction of errors such as:



STOP AND WAIT

- see example with both types of errors



GO BACK N

- most commonly used error control
- based on sliding-window
- use window size to control number of outstanding frames
- if no error, ACK as usual
- use window to control number of outstanding frames
- if error, reply with rejection
 - discard that frame and all future frames until error frame received correctly
 - transmitter must go back and retransmit that frame and all subsequent frames

GO BACK N - HANDLING

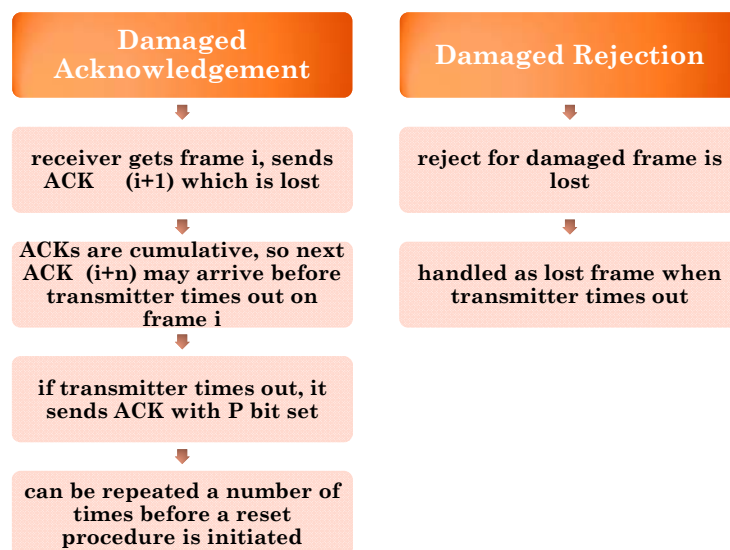
◦ Damaged Frame

- error in frame i so receiver rejects frame i
- transmitter retransmits frames from i

◦ Lost Frame

- frame i lost and either
 - transmitter sends $i+1$ and receiver gets frame $i+1$ out of seq and rejects frame i
 - or transmitter times out and send ACK with P bit set which receiver responds to with ACK i
- transmitter then retransmits frames from i

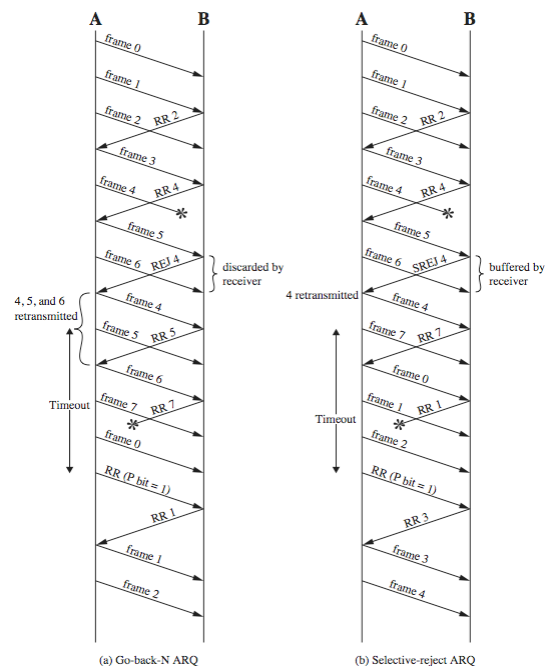
GO BACK N - HANDLING



SELECTIVE REJECT (ARQ)

- also called selective retransmission
- only rejected frames are retransmitted
- subsequent frames are accepted by the receiver and buffered
- minimizes retransmission
- receiver must maintain large enough buffer
- more complex logic in transmitter
- hence less widely used
- useful for satellite links with long propagation delays

GO BACK N VS SELECTIVE REJECT



PERFORMANCE ISSUES

○ Stop-and-Wait Flow Control

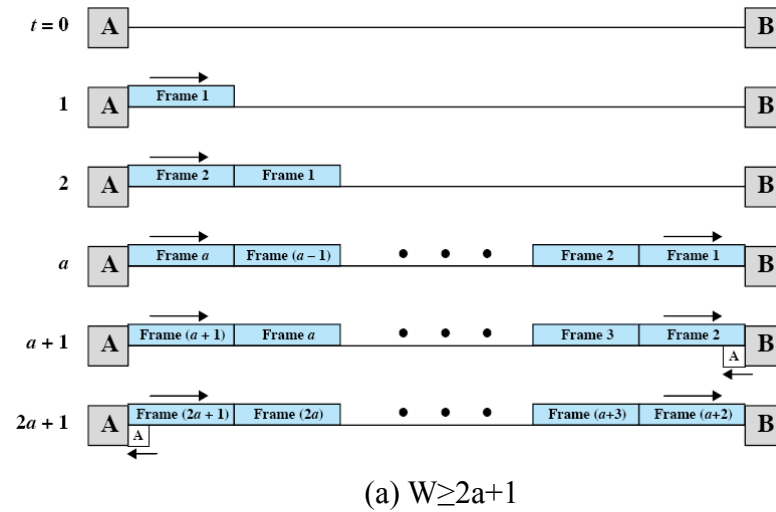
- T : the total time to send data, $T = nT_F$
- T_F : the total time to send one frame and receive an acknowledgement
- $T_F = t_{\text{prop}} + t_{\text{frame}} + t_{\text{proc}} + t_{\text{prop}} + t_{\text{ack}} + t_{\text{proc}}$
- Ignoring t_{proc} and t_{ack} , $T = n(2t_{\text{prop}} + t_{\text{frame}})$
- Utilization $U = nt_{\text{frame}} / T = t_{\text{frame}} / (2t_{\text{prop}} + t_{\text{frame}}) = 1 / (1 + 2a)$
where $a = t_{\text{prop}} / t_{\text{frame}}$

PERFORMANCE ISSUES

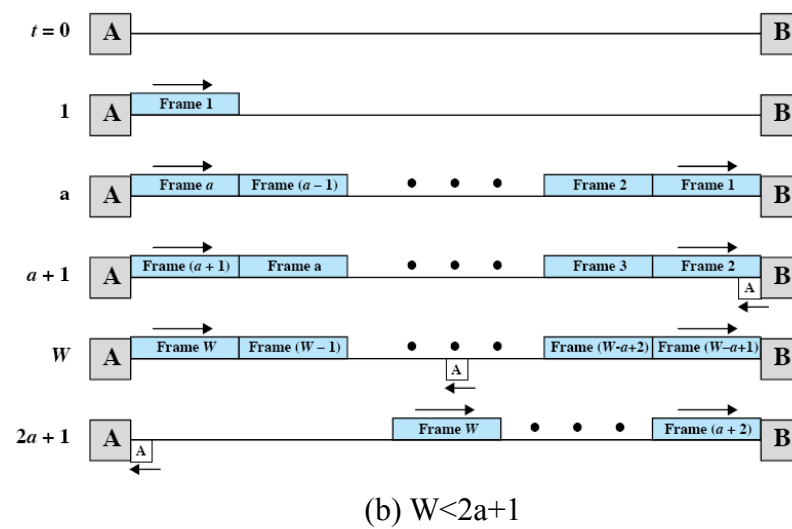
○ Error-Free Sliding-Window Flow Control

- The throughput on the line depends on both the window size W and the value of a
- Case 1: $W \geq 2a + 1$. The acknowledgement for frame 1 reaches A before A has exhausted its window.
- Case 2: $W < 2a + 1$. A exhausts its window at $t = W$ and cannot send additional frames until $t = 2a + 1$.

ERROR-FREE SLIDING-WINDOW FLOW CONTROL



ERROR-FREE SLIDING-WINDOW FLOW CONTROL

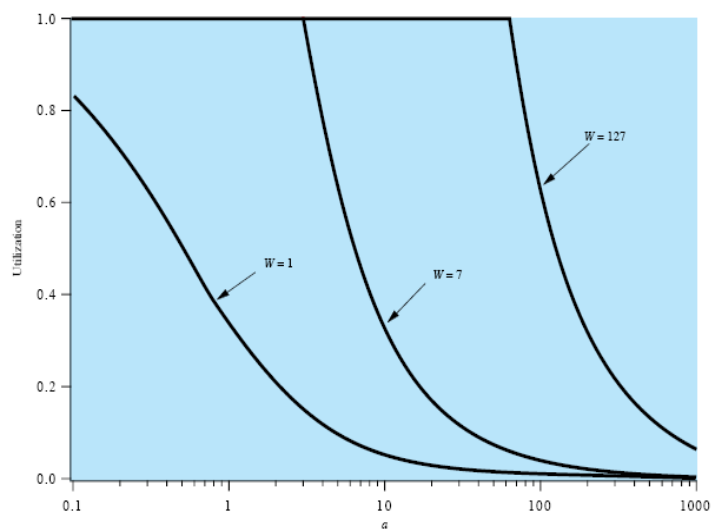


ERROR-FREE SLIDING-WINDOW FLOW CONTROL

Utilization

$$U = \begin{cases} \frac{1}{W} & W \geq 2a + 1 \\ \frac{1}{(2a + 1)} & W < 2a + 1 \end{cases}$$

ERROR-FREE SLIDING-WINDOW FLOW CONTROL



ARQ

◦ Stop-and-wait ARQ

$$U = \frac{T_f}{N_r T_t} = \frac{1}{N_r (1 + 2a)}$$

$$N_r = \frac{1}{1 - P}$$

$$U = \frac{1 - P}{1 + 2a}$$

ARQ

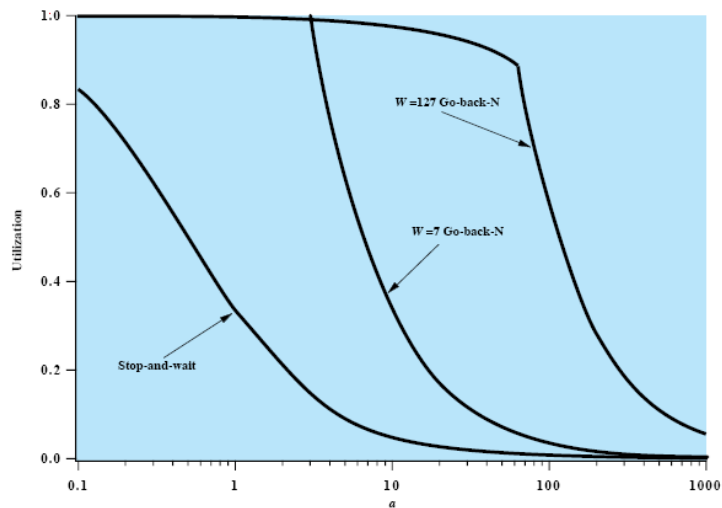
◦ Selective Reject

$$U = \begin{cases} \frac{1 - P}{W(1 - P)} & W \geq 2a + 1 \\ \frac{1}{2a + 1} & W < 2a + 1 \end{cases}$$

◦ Go-back-N

$$U = \begin{cases} \frac{1 - P}{1 + 2aP} & W \geq 2a + 1 \\ \frac{W(1 - P)}{(2a + 1)(1 - P + WP)} & W < 2a + 1 \end{cases}$$

ARQ



HIGH LEVEL DATA LINK CONTROL (HDLC)

- an important data link control protocol
- specified as ISO 3309, ISO 4335
- station types:
 - Primary - controls operation of link
 - Secondary - under control of primary station
 - Combined - issues commands and responses
- link configurations
 - Unbalanced - 1 primary, multiple secondary
 - Balanced - 2 combined stations

HDLC TRANSFER MODES

Normal Response Mode (NRM)

- used with an unbalanced configuration
- primary initiates transfer

Asynchronous Balanced Mode (ABM)

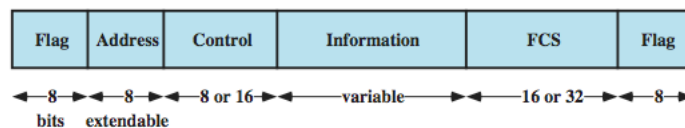
- used with a balanced configuration
- either station initiates transmission
- has no polling overhead
- most widely used

Asynchronous Response Mode (ARM)

- used with unbalanced configuration
- secondary may transmit without permission from primary
- rarely used

HDLC FRAME STRUCTURE

- synchronous transmission of frames
- single frame format used



(a) Frame format

FLAG FIELDS AND BIT STUFFING

- delimit frame at both ends with 01111110 seq
- receiver hunts for flag sequence to synchronize
- bit stuffing used to avoid confusion with data containing flag seq 01111110
 - 0 inserted after every sequence of five 1s
 - if receiver detects five 1s it checks next bit
 - if next bit is 0, it is deleted (was stuffed bit)
 - if next bit is 1 and seventh bit is 0, accept as flag
 - if sixth and seventh bits 1, sender is indicating abort

Original Pattern:

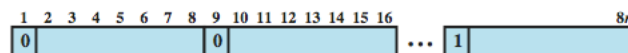
111111111110111110111110

After bit-stuffing

1111101111101101111101011111010

ADDRESS FIELD

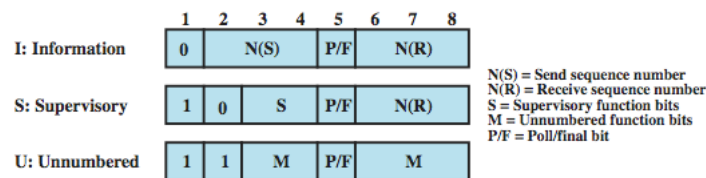
- identifies secondary station that sent or will receive frame
- usually 8 bits long
- may be extended to multiples of 7 bits
 - LSB indicates if is the last octet (1) or not (0)
- all ones address 11111111 is broadcast



(b) Extended Address Field

CONTROL FIELD

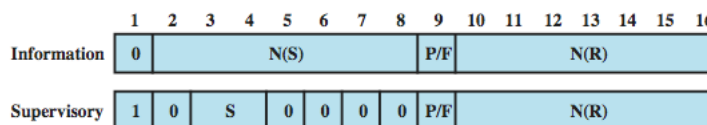
- different for different frame type
 - Information - data transmitted to user (next layer up)
 - Flow and error control piggybacked on information frames
 - Supervisory - ARQ when piggyback not used
 - Unnumbered - supplementary link control
- first 1-2 bits of control field identify frame type



(c) 8-bit control field format

CONTROL FIELD

- use of Poll/Final bit depends on context
- in command frame is P bit set to 1 to solicit (poll) response from peer
- in response frame is F bit set to 1 to indicate response to soliciting command
- seq number usually 3 bits
 - can extend to 8 bits as shown below



(d) 16-bit control field format

INFORMATION & FCS FIELDS

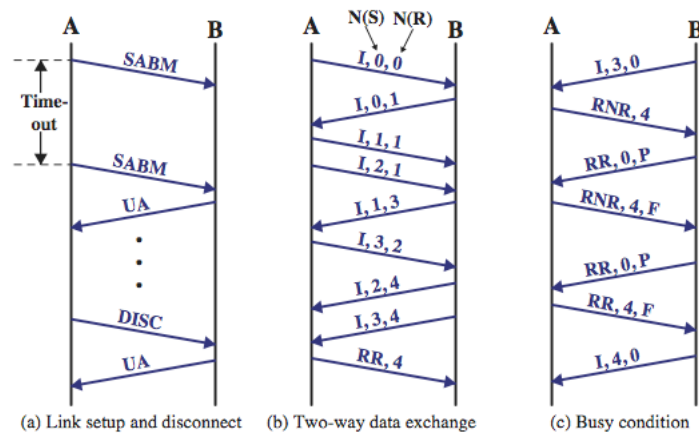
Information Field

- in information and some unnumbered frames
- must contain integral number of octets
- variable length

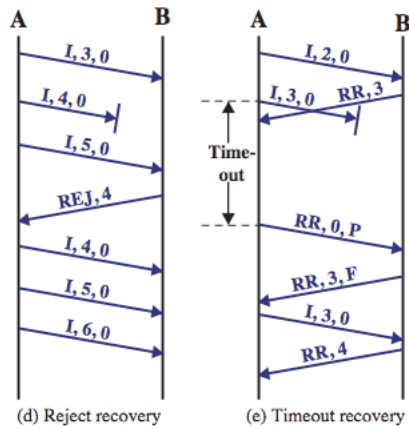
Frame Check Sequence Field (FCS)

- used for error detection
- either 16 bit CRC or 32 bit CRC

HDLC OPERATION EXAMPLE



HDLC OPERATION EXAMPLE



SUMMARY

- introduced need for data link protocols
- flow control
- error control
- HDLC