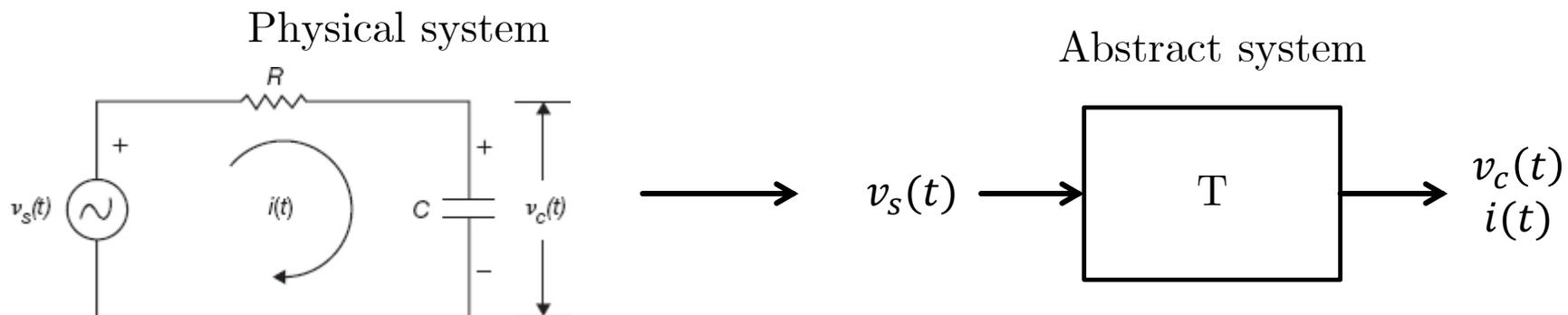


# EE361: SIGNALS AND SYSTEMS II

## REVIEW SIGNALS AND SYSTEMS I

# SIGNALS AND SYSTEMS I RECAP

- Signals – quantitative descriptions of physical phenomena
  - Represent a pattern of variation
- System – quantitative description of a physical process to transform an input signal to an output signal
  - The system is a “black box”
- E.g.



# SIGNALS

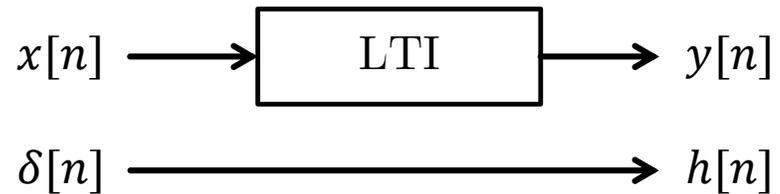
- This course deals with signals that are a function of one variable
  - Most often called “time”
- Continuous time (CT) signal
  - $x(t), t \in \mathbb{R}$
  - Time is a real valued (e.g. 1.23 seconds)
- Discrete time (DT) signal
  - $x[n], n \in \mathbb{Z}$
  - Time is discrete (e.g. 1 or 5)
    - Signal is a sequence and  $n$  is the location within the sequence

# BASIC SYSTEM PROPERTIES

- Memoryless
  - Output does not depend on past/future values
- Invertible
  - Another system exists that accepts  $y(t)$  as input and returns  $x(t)$
- Causal
  - Output only depends on past or present values
  - Realizable system since it does not need future values
    - Implement non-causal systems with delays
- Stable
  - BIBO criterion: bounded input results in bounded output
- Linear
  - Given  $T[x(t)] \rightarrow y(t)$
  - $ax_1(t) + bx_2(t) \rightarrow ay_1(t) + by_2(t)$
- Time Invariant
  - Time shift on input results in same time shift on output
  - $T[x(t - t_0)] \rightarrow y(t - t_0)$

# LTI SYSTEM

- Linear and time-invariant systems

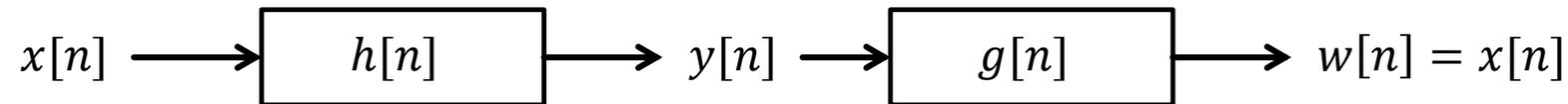


- Impulse response  $h[n]$  completely specifies input/output relationship

$x[n] \longrightarrow \boxed{h[n]} \longrightarrow y[n] = x[n] * h[n]$   
 $= \sum_{k=-\infty}^{\infty} x[k]h[n-k]$   
 $= \sum_{k=-\infty}^{\infty} h[k]x[n-k]$

# LTI PROPERTIES

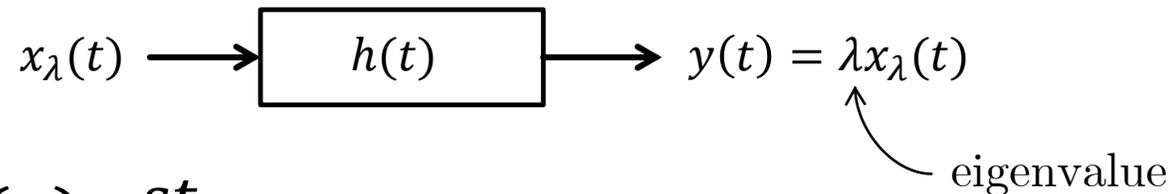
- Memoryless
  - $h(t) = a\delta(t)$ , where  $a$  is a constant
- Invertible



- $h[n] * g[n] = \delta[n]$
- Causal
  - $h(t) = 0, t < 0$
  - Does not depend on future input – see convolution integral
- Stable
  - Absolutely integrable/summable
  - $\int_{-\infty}^{\infty} |h(\tau)| d\tau < \infty$

# EIGEN PROPERTY

- Eigen function (signal) for an LTI system is a signal for which the output is the input times a (complex) constant



- CT:  $e^{st} \rightarrow H(s)e^{st}$ 
  - $H(s)$  – eigenvalue from Laplace Transform (system/transfer function)
- DT:  $z^n \rightarrow H(z)z^n$ 
  - $H(z)$  - eigenvalue from Z-transform (system/transfer function)